

**Python Level 1 with Virtual Robotics**  
**Mission 7 Objective 2 Line Sensor Readings**

**Name:**

Use this document to chart the line sensor readings while rotating around the compass rose.

- Look for line sensor readings where the left and right are different.
- The right reading will become the left reading when the 'bot is on the next compass point.
- Your readings may be a little different from another person's bot.

	<b>Compass Point</b>	<b>Left Reading</b>	<b>Right Reading</b>
	<b>West</b>	2481	3019
	<b>North West</b>	3019	
	<b>North</b>		
	<b>North East</b>		
	<b>East</b>		
	<b>South East</b>		
	<b>South</b>		
	<b>South West</b>		